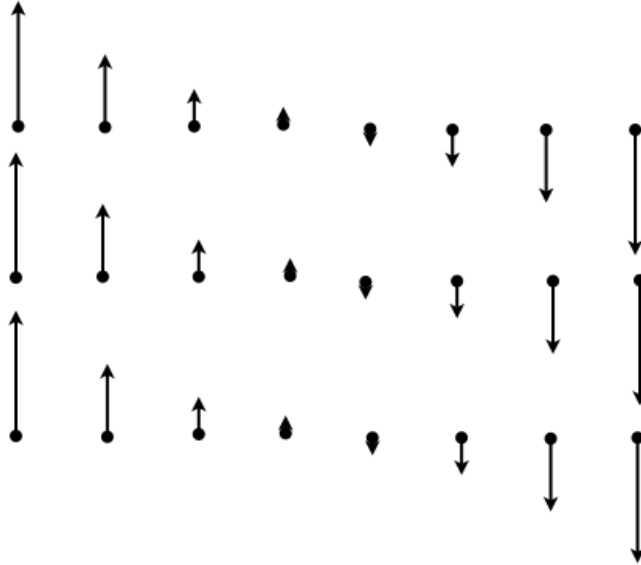


What is the curl ($\nabla \times \mathbf{F}$) of this vector field, \mathbf{F} ?

- A) = 0 everywhere
C) = 0 in some places

- B) $\neq 0$ everywhere
D) Not enough info to decide

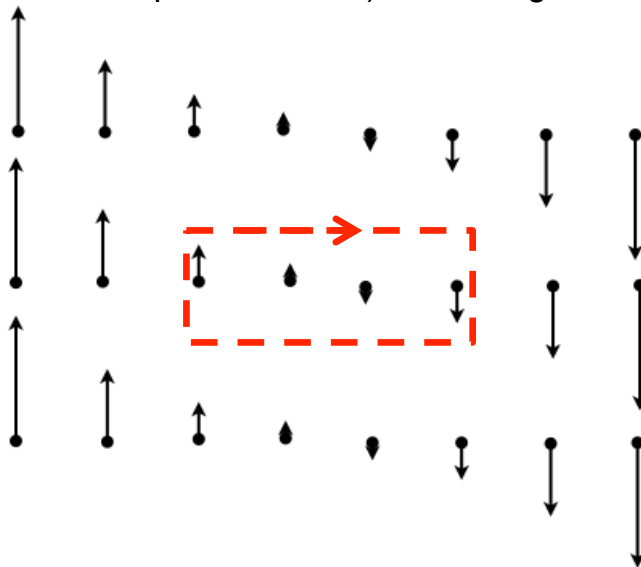


2- 1

What is the curl ($\nabla \times \mathbf{F}$) of this vector field, \mathbf{F} ?

- A) = 0 everywhere
C) = 0 in some places

- B) $\neq 0$ everywhere
D) Not enough info to decide



2- 2

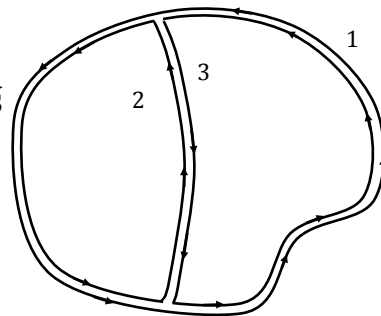
Last class: the following are basically all equivalent!

- $\mathbf{F}(\mathbf{r})$ is a conservative force
- $\int_{r_0}^{r_1} \vec{\mathbf{F}}(\mathbf{r}') \cdot d\vec{\mathbf{r}}'$ is path independent
- PE is well defined $U(\mathbf{r}) = -\int_{r_0}^{\mathbf{r}} \vec{\mathbf{F}}(\mathbf{r}') \cdot d\vec{\mathbf{r}}'$
- $\vec{\mathbf{F}}(\mathbf{r}) = -\vec{\nabla} U(\mathbf{r})$
- $\vec{\nabla} \times \vec{\mathbf{F}}(\mathbf{r}) = \mathbf{0}$
- $\oint \vec{\mathbf{F}}(\mathbf{r}') \cdot d\vec{\mathbf{r}}' = \mathbf{0}$

2-

Consider the three closed paths 1, 2, and 3 in some vector field \mathbf{F} , where paths 2 and 3 cover the larger path 1 as shown. What can you say about the 3 path integrals?

- A) $\oint_1 \vec{\mathbf{F}} \cdot d\vec{\mathbf{s}} > \oint_2 \vec{\mathbf{F}} \cdot d\vec{\mathbf{s}} + \oint_3 \vec{\mathbf{F}} \cdot d\vec{\mathbf{s}}$
- B) $\oint_1 \vec{\mathbf{F}} \cdot d\vec{\mathbf{s}} < \oint_2 \vec{\mathbf{F}} \cdot d\vec{\mathbf{s}} + \oint_3 \vec{\mathbf{F}} \cdot d\vec{\mathbf{s}}$
- C) $\oint_1 \vec{\mathbf{F}} \cdot d\vec{\mathbf{s}} = \oint_2 \vec{\mathbf{F}} \cdot d\vec{\mathbf{s}} + \oint_3 \vec{\mathbf{F}} \cdot d\vec{\mathbf{s}}$

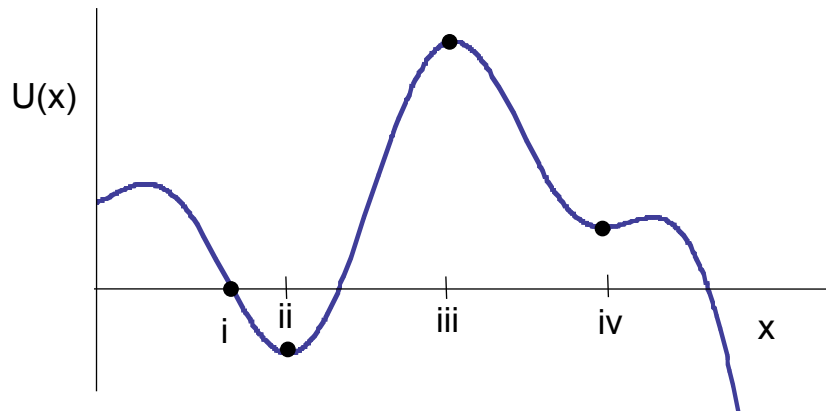


- D) There is no way to decide without knowing $\vec{\mathbf{F}}$

2- 5

Of the four labeled points, at which is the force = 0 ?

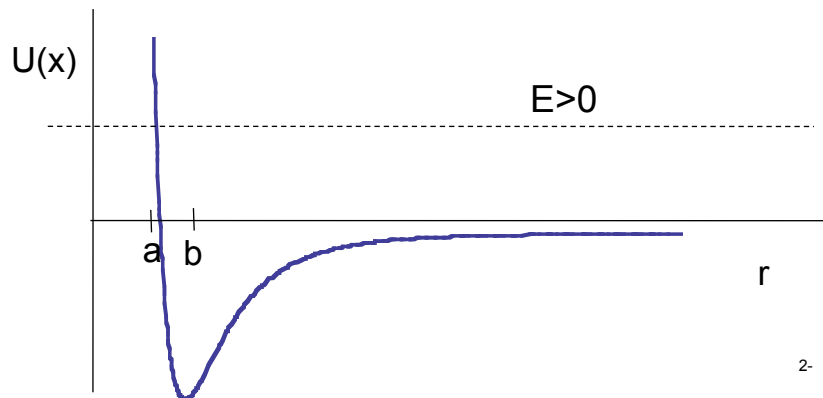
- A) i only B) ii only
 C) ii & iv only D) ii, iii and iv only
 E) Some other combination!



2- 7

Fig 4.12 of Taylor shows PE of H in an HCl molecule. If the energy, E , is shown (dashed), what's the best description of the motion of the H atom?

- A) Trapped, at $r=a$ B) Oscillates around $r=b$
 C) Unbound, the H "escapes" D) Other/????

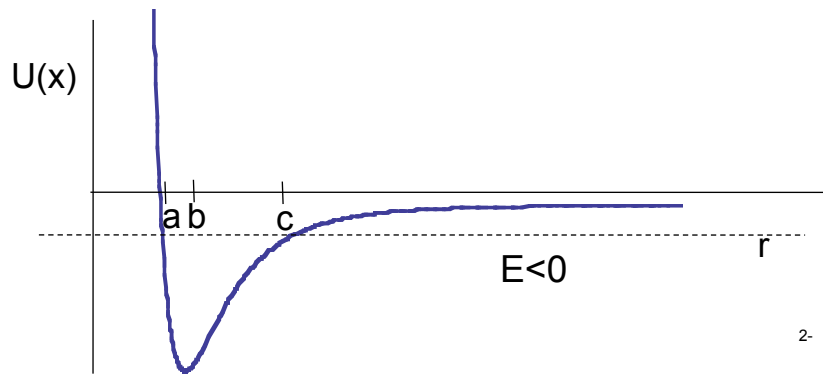


2- 8

Fig 4.12 of Taylor shows PE of H in an HCl molecule.

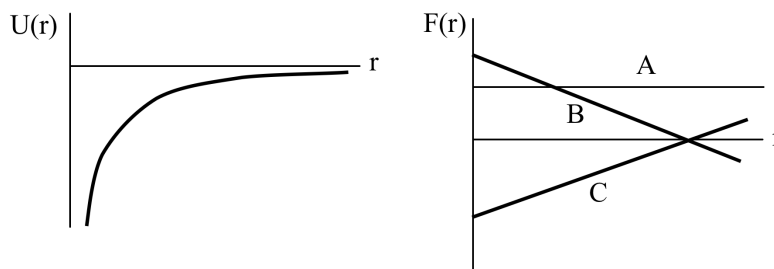
If the energy, E , is shown (dashed), what's the best description of the motion of the H?

- A) Trapped, at $r=a$
- B) Trapped, at a OR c
- C) Unbound, H "escapes"
- D) Oscillates around $r=b$
- E) Other/???



2- 9

The potential energy of a test mass is shown as a function of distance from the origin $U(r) \sim -1/r$. Which graph shows the corresponding force as a function of distance?



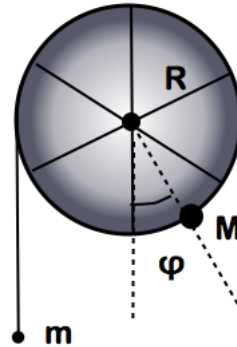
D) None of these!

2- 11

Consider this massless frictionless wheel.
 M is attached to the side, while m hangs from a string wrapped around the wheel.

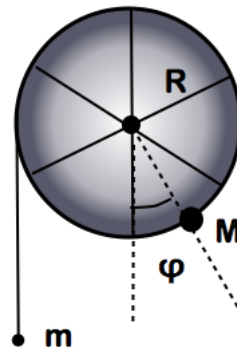
What is the potential energy of m in terms of φ ?

- A) $+mg\varphi$
- B) $-mg\varphi$
- C) $+mgR\varphi$
- D) $-mgR\varphi$
- E) Something else, there's got to be some trig!



What is the potential energy of M in terms of φ ?

- A) $MgR\cos(\varphi)$
- B) $MgR\sin(\varphi)$
- C) $MgR(\cos(\varphi)-1)$
- D) $MgR(1-\cos(\varphi))$
- E) Something else!



Summary:

- 1-D systems, $U(x)$ yields $F(x)=-dU/dx$
- Equilibrium when $U'(x)=0$
- Stable Equilibrium if $U''(x)>0$
- Plots of $U(x)$ vs x give us immediate information (about binding, motion, $v(x)$, $v(t)$, equilibrium, ...)
-

2- 18