

Physics 3210

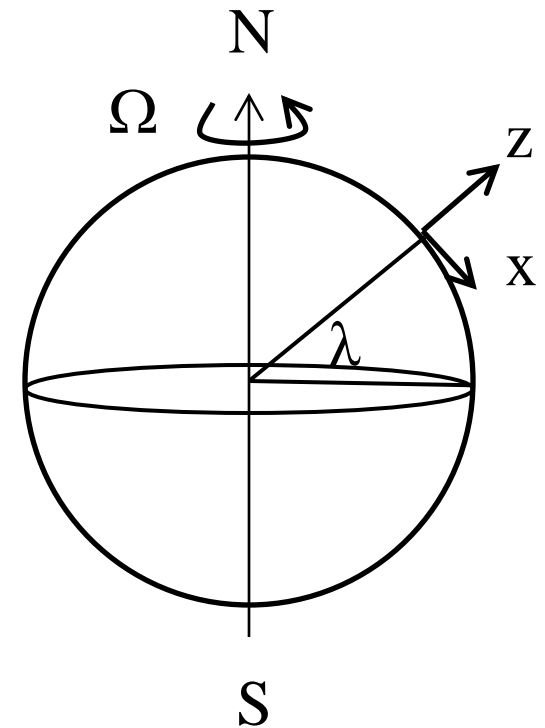
Week 10 clicker questions

Consider a Foucault pendulum in the northern hemisphere. We derived the motion of the pendulum in the absence of rotation as $x'(t)$, $y'(t)$. When rotation of the earth is included, we find

$$\begin{bmatrix} x(t) \\ y(t) \end{bmatrix} = \begin{bmatrix} \cos\Omega_z t & \sin\Omega_z t \\ -\sin\Omega_z t & \cos\Omega_z t \end{bmatrix} \begin{bmatrix} x'(t) \\ y'(t) \end{bmatrix}$$

What is the effect of multiplying by the matrix?

- A. The x' , y' solution is reflected about a time-dependent axis.
- B. The x' , y' solution is reflected about a fixed axis.
- C. The x' , y' solutions is rotated through a fixed angle.
- D. The x' , y' solution is rotated through a time-dependent angle.

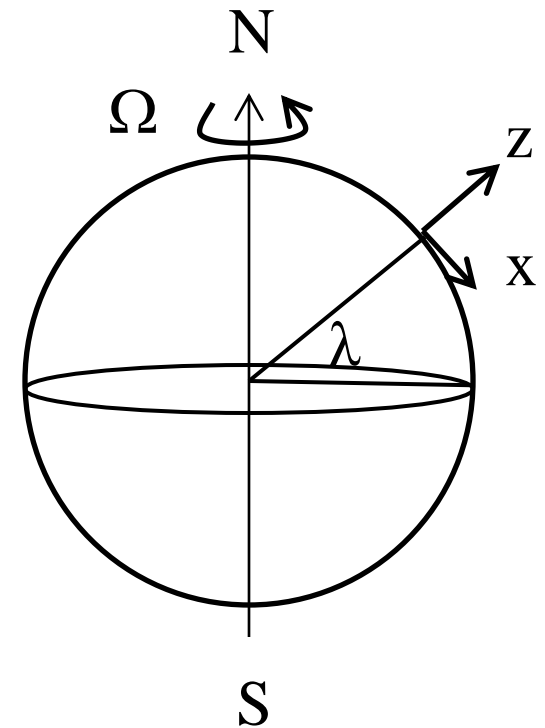


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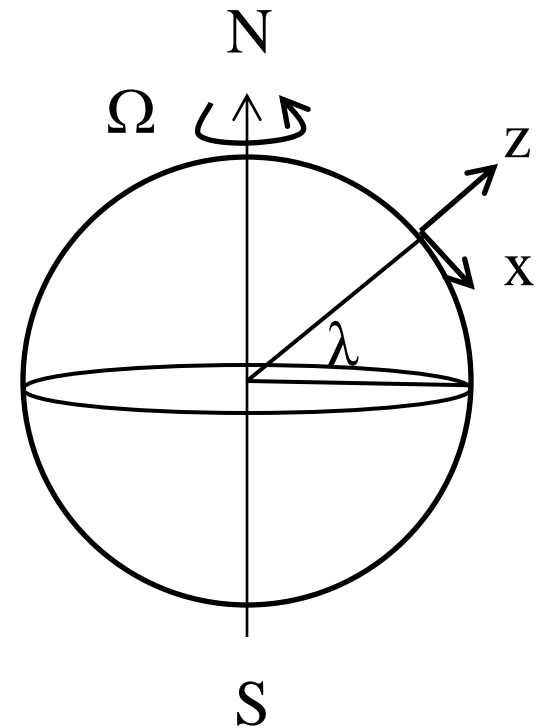
What is precession frequency of the pendulum?

- A. Ω
- B. $\Omega \sin\lambda$
- C. $\Omega \cos\lambda$
- D. None of the above.



Consider a Foucault pendulum in the northern hemisphere. Where does the pendulum precess most rapidly?

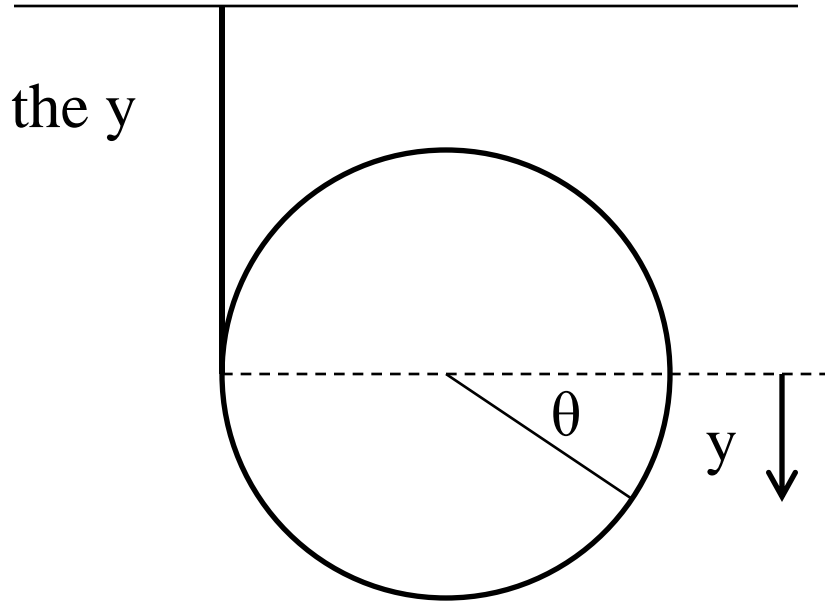
- A. At the equator.
- B. At 30 degrees N latitude.
- C. At 45 degrees N latitude.
- D. At 60 degrees N latitude.
- E. At the north pole.



A cylinder (mass M , radius R) is suspended from a string wrapped around its edge. The cylinder is released from rest; it then falls and the string unwraps. The tension in the string has magnitude T .

What is the net force on the cylinder (in the y direction)?

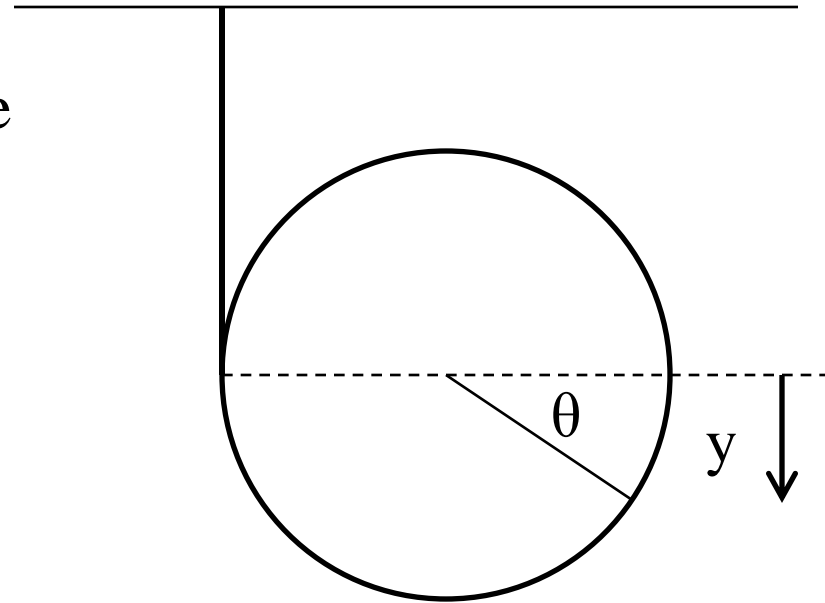
- A. $F = Mg$
- B. $F = -T$
- C. $F = Mg - T$
- D. $F = T - Mg$



A cylinder (mass M , radius R) is suspended from a string wrapped around its edge. The cylinder is released from rest; it then falls and the string unwraps. The tension in the string has magnitude T .

What are the sources of torque about the central axis of the cylinder?

- A. Gravity.
- B. Tension in the string.
- C. Both gravity and tension in the string.
- D. Neither gravity nor tension in the string.



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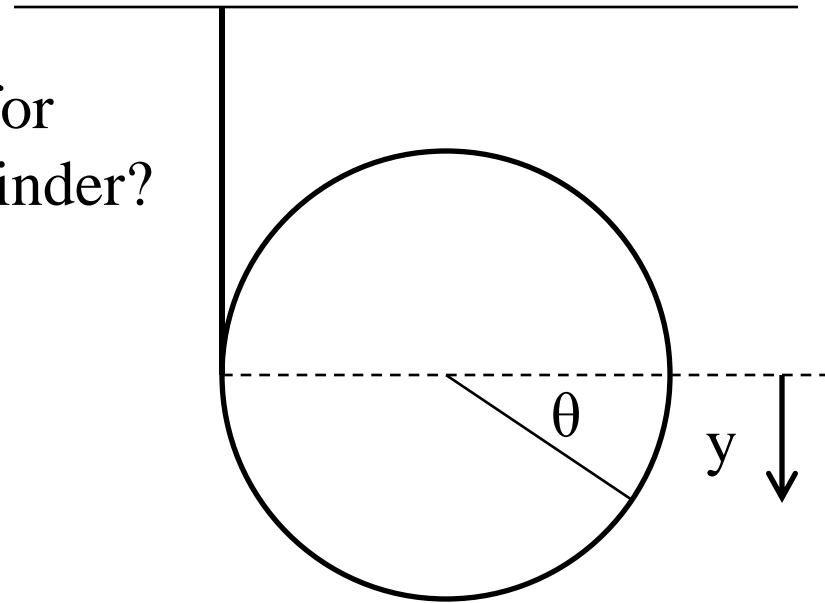
What is the correct equation of motion for rotation about the central axis of the cylinder?

A. $I\ddot{\theta} = T$

B. $I\ddot{\theta} = -T$

C. $I\ddot{\theta} = RT$

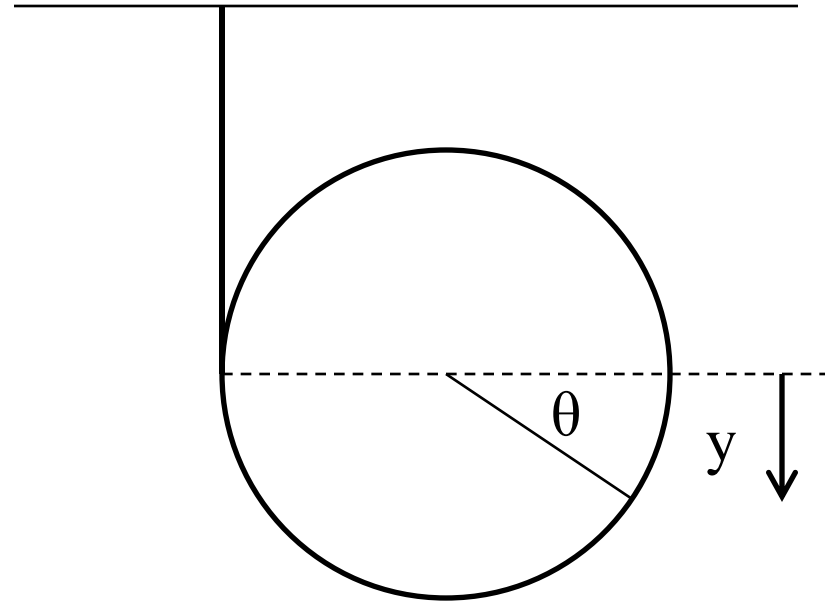
D. $I\ddot{\theta} = -RT$



A cylinder (mass M , radius R) is suspended from a string wrapped around its edge. The cylinder is released from rest; it then falls and the string unwraps. The tension in the string has magnitude T .

What is the tension in the string?

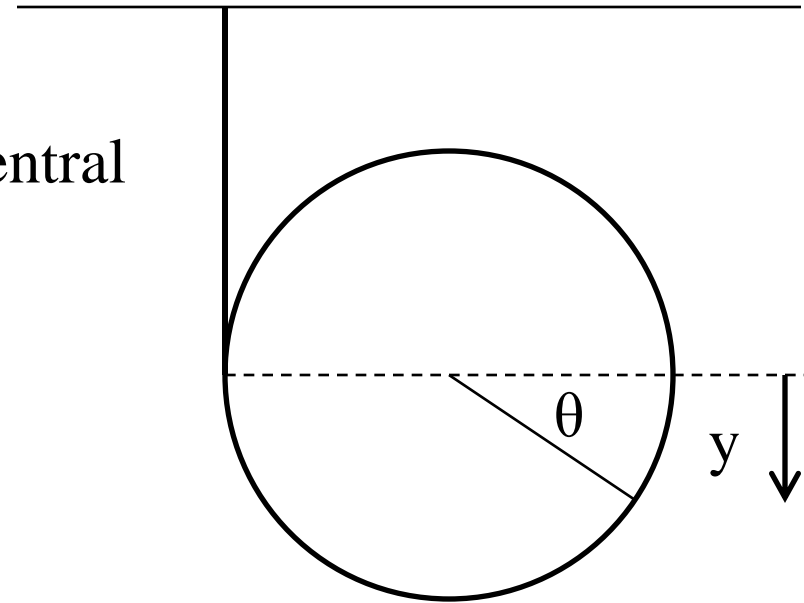
- A. $T = \frac{1}{3}Mg$
- B. $T = \frac{2}{3}Mg$
- C. $T = Mg$
- D. $T = \frac{4}{3}Mg$



A cylinder (mass M , radius R) is suspended from a string wrapped around its edge. The cylinder is released from rest; it then falls and the string unwraps. The tension in the string has magnitude T .

What is the angular velocity about the central axis of the cylinder?

- A. $\dot{\theta} = \frac{gt}{3}$
- B. $\dot{\theta} = \frac{2gt}{3}$
- C. $\dot{\theta} = \frac{gt}{3R}$
- D. $\dot{\theta} = \frac{2gt}{3R}$



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Wednesday clicker questions

A system of n particles is described by the masses and positions of each particle, relative to the center of mass: $m_\alpha, \mathbf{r}_\alpha$

What can you say about the quantity $\sum_{\alpha} m_{\alpha} \mathbf{r}_{\alpha}$?

A. $\sum_{\alpha} m_{\alpha} \mathbf{r}_{\alpha} = 0$

B. $\sum_{\alpha} m_{\alpha} \mathbf{r}_{\alpha} > 0$

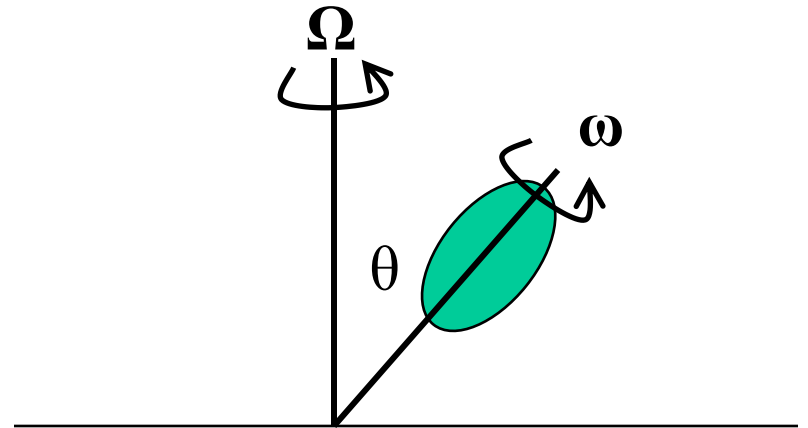
C. $\sum_{\alpha} m_{\alpha} \mathbf{r}_{\alpha} < 0$

D. $\sum_{\alpha} m_{\alpha} \mathbf{r}_{\alpha} = \text{the position of the CM}$

A top spins about its own symmetry axis (angular velocity ω) and precesses about the vertical (angular velocity Ω).

How does the precession rate depend on the rotation rate?

- A. Ω increases as ω increases.
- B. Ω is independent of ω .
- C. Ω decreases as ω increases.
- D. It depends on the angle.

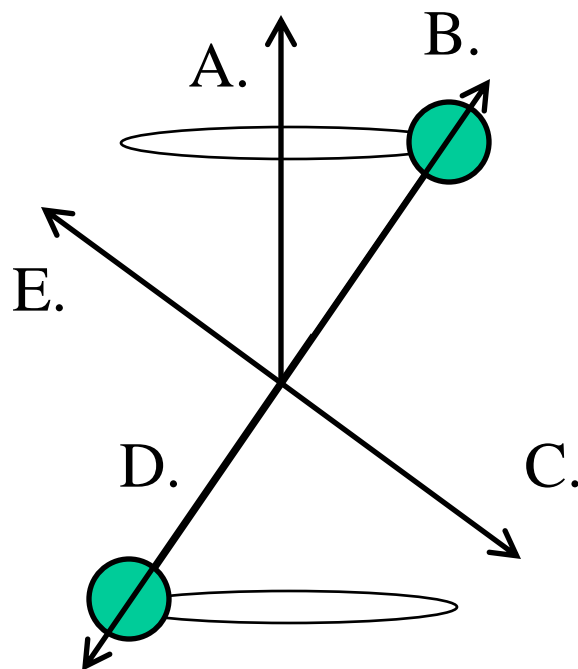
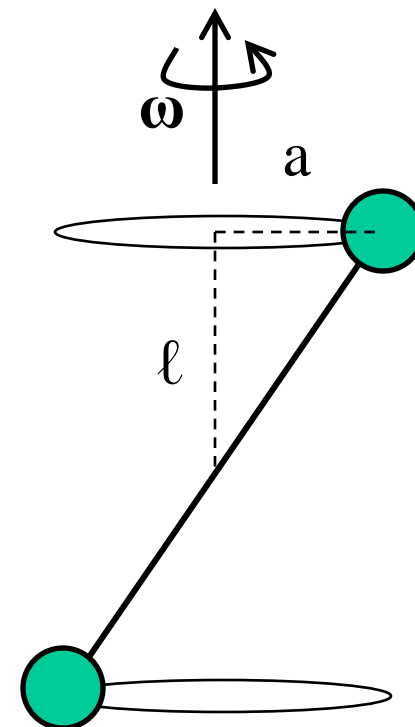


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Friday clicker questions

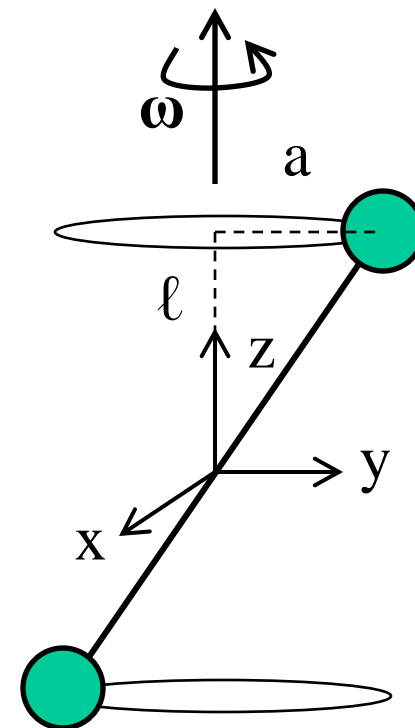
A rotating dumbbell consists of two masses (mass m) which move in circles (radius a) at z displacement ℓ and $-\ell$, joined by a massless rod. The angular velocity vector $\boldsymbol{\omega} = \omega \hat{\mathbf{z}}$

What is the direction of the angular momentum vector \mathbf{L} ?



A rotating dumbbell consists of two masses (mass m) which move in circles (radius a) at z displacement ℓ and $-\ell$, joined by a massless rod. The angular velocity vector $\boldsymbol{\omega} = \omega \hat{\mathbf{z}}$

Consider the body frame where the positions of the masses are $(0, a, \ell)$ and $(0, -a, -\ell)$. What is the I_{33} component of the inertia tensor?



A. $I_{33} = \frac{1}{2} m a^2$

D. $I_{33} = m \ell^2$

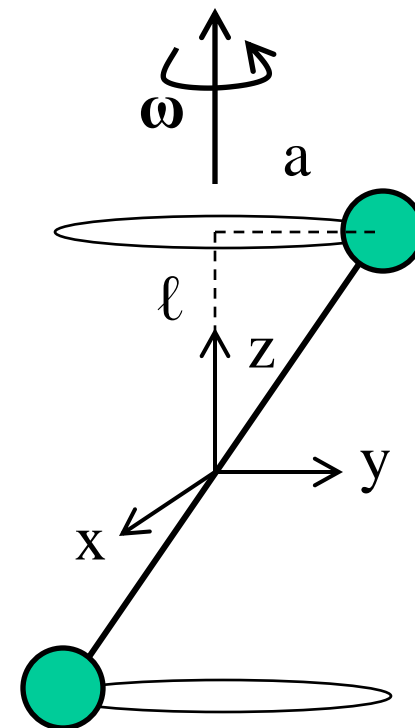
B. $I_{33} = m a^2$

E. $I_{33} = 2 m \ell^2$

C. $I_{33} = 2 m a^2$

A rotating dumbbell consists of two masses (mass m) which move in circles (radius a) at z displacement ℓ and $-\ell$, joined by a massless rod. The angular velocity vector $\boldsymbol{\omega} = \omega \hat{\mathbf{z}}$

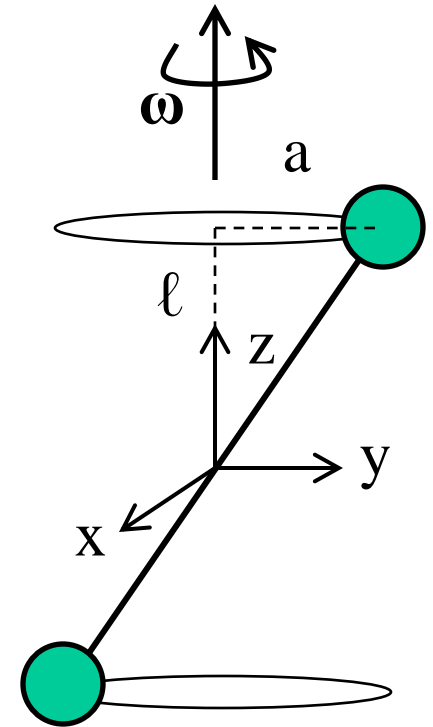
Consider the body frame where the positions of the masses are $(0, a, \ell)$ and $(0, -a, -\ell)$. What is the I_{13} component of the inertia tensor?



- A. $I_{13} = 2mal$ D. $I_{13} = -mal$
- B. $I_{13} = mal$ E. $I_{13} = 0$
- C. $I_{13} = -2mal$

A rotating dumbbell consists of two masses (mass m) which move in circles (radius a) at z displacement ℓ and $-\ell$, joined by a massless rod. The angular velocity vector $\boldsymbol{\omega} = \omega \hat{\mathbf{z}}$

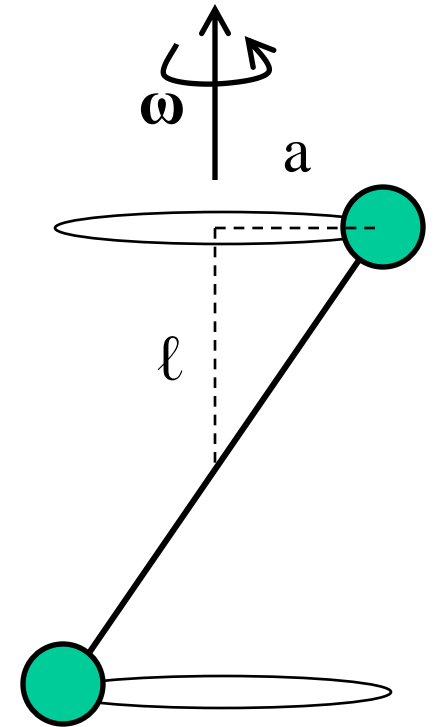
Consider the body frame where the positions of the masses are $(0, a, \ell)$ and $(0, -a, -\ell)$. What is the I_{23} component of the inertia tensor?



- A. $I_{23} = 2mal$ D. $I_{23} = -mal$
- B. $I_{23} = mal$ E. $I_{23} = 0$
- C. $I_{23} = -2mal$

A rotating dumbbell consists of two masses (mass m) which move in circles (radius a) at z displacement ℓ and $-\ell$, joined by a massless rod. The angular velocity vector $\boldsymbol{\omega} = \omega \hat{\mathbf{z}}$

What is the kinetic energy of the system?



- A. $T = 2ma^2\omega^2$ D. $T = -2ma^2\omega^2$
- B. $T = ma^2\omega^2$ E. $T = 0$
- C. $T = \frac{1}{2}ma^2\omega^2$

The inertia tensor is a 3-by-3 matrix with real positive eigenvalues and orthogonal eigenvectors.

As a result, how many of the following statements are true?

1. The matrix can be diagonalized.
2. The matrix of eigenvectors is an orthogonal matrix.
3. The matrix of eigenvectors is a rotation matrix (if properly normalized).
4. In the coordinate system aligned with the eigenvectors, the inertia tensor is diagonal.

- A. None are true.
- B. Exactly one is true.
- C. Exactly two are true.
- D. Exactly three are true.
- E. All four are true.