Physics 3210

Week 9 clicker questions



Which of the following types of motion lead to fictitious forces (in the moving reference frame)?

1. The frame moves at a constant velocity with respect to an inertial reference frame.

2. The frame rotates at a constant angular velocity with respect to an inertial reference frame.

3. The frame moves at a constant acceleration with respect to an inertial reference frame.

4. The frame rotates at a constant angular acceleration with respect to an inertial reference frame.

- A. None
- B. Exactly one
- C. Exactly two
- D. Exactly three
- E. All four

For a rotating coordinate frame with the rotation aligned with the z axis, we derived that

$$x\frac{d\hat{x}}{dt} + y\frac{d\hat{y}}{dt} + z\frac{d\hat{z}}{dt} = (-x\Omega\sin\theta\sin\Omega t, y\Omega\sin\theta\cos\Omega t, 0)$$

How can this expression be rewritten in vector notation?

A. $\mathbf{r} \cdot \mathbf{\Omega}$

- B. $(\mathbf{\Omega} \times \mathbf{r}) \cdot \mathbf{\Omega}$
- C. $(\mathbf{\Omega} \times \mathbf{r}) \cdot \mathbf{r}$

D. $\Omega \times r$

The coriolis and centrifugal "forces" are

$$\mathbf{F}_{\text{coriolis}} = -2\mathbf{m}\mathbf{\Omega} \times \mathbf{v}$$
$$\mathbf{F}_{\text{centrifugal}} = -\mathbf{m}\mathbf{\Omega} \times (\mathbf{\Omega} \times \mathbf{r})$$

Which force is more important in the limit of slow velocity (in the rotating frame)?

- A. Coriolis force
- B. Centrifugal force
- C. They are equally important
- D. Neither is important
- E. More information is needed to answer

The coriolis and centrifugal "forces" are

 $\mathbf{F}_{\text{coriolis}} = -2\mathbf{m}\mathbf{\Omega} \times \mathbf{v}$ $\mathbf{F}_{\text{centrifugal}} = -\mathbf{m}\mathbf{\Omega} \times (\mathbf{\Omega} \times \mathbf{r})$

A disk drive typically rotates at about 3600 rpm = 360 radians/sec. For a dust particle at a radius r=5 cm, how fast must the particle be moving (in the rotating frame) for the coriolis and centrifugal forces to have approximately equal magnitude?

- A. 9 cm/sec
- B. 90 cm/sec
- C. 900 cm/sec
- D. 9000 cm/sec



A bead rests on a wire that extends from the origin at and angle θ to the vertical; the wire rotates with angular velocity Ω about the vertical. In the frame rotating with the wire, what is the magnitude and direction of the centrifugal force when the bead is a distance r from the origin?

- A. $m\Omega^2 r \sin\theta$, away from the rotation axis
- B. $m\Omega^2 r \sin\theta$, towards from the rotation axis
- C. $m\Omega^2 r \cos\theta$, away from the rotation axis
- D. $m\Omega^2 r \cos\theta$, towards from the rotation axis

A bucket of water spins about its central axis. After a relaxation time the shape of the water surface reaches a steady state. Where is the water surface highest?

- A. The water is highest at the center of the bucket.
- B. The water is highest at a point intermediate between the center and edge of the bucket.
- C. The water is highest at the edge of the bucket.
- D. The answer depends on the rotation rate.

A hockey puck slides from the center towards the edge of a frictionless, rotating merry-go-round. The merry-go-round has angular velocity Ω and rotates CCW when viewed from above. In the rotating frame, the initial velocity is in the positive y direction. In the <u>inertial</u> frame, which way does the path of the puck bend?

- A. The path curves to the right when viewed from above (towards positive x).
- B. The path doesn't curve.
- C. The path curves to the left when viewed from above (towards negative x).
- D. The answer depends on the rotation rate.



A hockey puck slides from the center towards the edge of a frictionless, rotating merry-go-round. The merry-go-round has angular velocity Ω and rotates CCW when viewed from above. In the rotating frame, the initial velocity is in the positive y direction. In the <u>rotating</u> frame, which way does the path of the puck bend?

- A. The path curves to the right when viewed from above (towards positive x).
- B. The path doesn't curve.
- C. The path curves to the left when viewed from above (towards negative x).
- D. The answer depends on the rotation rate.



A hockey puck slides from the center towards the edge of a frictionless, rotating merry-go-round. The merry-go-round has angular velocity Ω and rotates CCW when viewed from above. In the rotating frame, the initial velocity is in the positive y direction.

Below are two different paths taken by the puck in the rotating frame. Which correspond to motion with a larger initial velocity?



- C. It cannot be determined from the information given.
- D. The answer depends on the rotation rate Ω .

A hockey puck slides from the center towards the edge of a frictionless, rotating merry-go-round. The merry-go-round has angular velocity Ω and rotates CCW when viewed from above. In the rotating frame, the initial velocity is in the positive y direction.

What effect does the Coriolis force have on the velocity of the puck?

- A. The Coriolis force changes the magnitude of the velocity, but not the direction.
- B. The Coriolis force changes the direction of the velocity, but not the magnitude.
- C. The Coriolis force changes both the magnitude and the direction of the velocity.
- D. The answer depends on the rotation rate.



Physics 3210

Friday clicker questions

A hockey puck slides from the center towards the edge of a frictionless, rotating merry-go-round. The merry-go-round has radius a, angular velocity Ω and rotates CCW when viewed from above. In the rotating frame, the initial velocity is in the positive y direction; neglect the centrifugal force.

How many rotations does the merry-go-round make before the puck slides off the edge?



At which of these points will a person's measured weight be <u>largest</u>?

A. At the equator.

- B. At 30 degrees N latitude.
- C. At 45 degrees N latitude.
- D. At 60 degrees N latitude.
- E. At the north pole.



In the <u>northern</u> hemisphere, what direction are winds from the north and south deflected by the Coriolis force?

- A. Winds from the N are deflected E and winds from the S are deflected W.
- B. Winds from the N are deflected E and winds from the S are deflected E.
- C. Winds from the N are deflected W and winds from the S are deflected W.
- D. Winds from the N are deflected W and winds from the S are deflected E.



Consider a Foucault pendulum in the northern hemisphere. The latitude is λ and we are using coordinates where x points towards the equator, y points parallel to a latitude line, and z points away from the center of the earth. What is the rotation vector in this coordinate system?



C.
$$\Omega = \Omega \begin{bmatrix} -\sin\lambda \\ 0 \\ \cos\lambda \end{bmatrix}$$
 D. $\Omega = \Omega \begin{bmatrix} \sin\lambda \\ 0 \\ \cos\lambda \end{bmatrix}$



Consider a Foucault pendulum in the northern hemisphere. The latitude is λ and we are using coordinates where x points towards the equator, y points parallel to a latitude line, and z points away from the center of the earth. What is the cross product of the rotation and velocity vectors in this coordinate system? N

A.
$$\mathbf{\Omega} \times \mathbf{v} = \begin{bmatrix} -\dot{\mathbf{x}} \Omega \sin \lambda \\ \dot{\mathbf{y}} \Omega \sin \lambda \\ -\dot{\mathbf{x}} \Omega \cos \lambda \end{bmatrix}$$
 B. $\mathbf{\Omega} \times \mathbf{v} = \begin{bmatrix} -\dot{\mathbf{x}} \Omega \cos \lambda \\ \dot{\mathbf{y}} \Omega \cos \lambda \\ -\dot{\mathbf{x}} \Omega \sin \lambda \end{bmatrix}$
C. $\mathbf{\Omega} \times \mathbf{v} = \begin{bmatrix} -\dot{\mathbf{y}} \Omega \sin \lambda \\ \dot{\mathbf{x}} \Omega \sin \lambda \\ -\dot{\mathbf{y}} \Omega \cos \lambda \end{bmatrix}$ D. $\mathbf{\Omega} \times \mathbf{v} = \begin{bmatrix} -\dot{\mathbf{y}} \Omega \cos \lambda \\ \dot{\mathbf{x}} \Omega \cos \lambda \\ -\dot{\mathbf{y}} \Omega \sin \lambda \end{bmatrix}$ S

Consider a Foucault pendulum in the northern hemisphere. We derived the motion of the pendulum in the absence of rotation as x'(t), y'(t). When rotation of the earth is included, we find

$$\begin{bmatrix} x(t) \\ y(t) \end{bmatrix} = \begin{bmatrix} \cos\Omega_z t & \sin\Omega_z t \\ -\sin\Omega_z t & \cos\Omega_z t \end{bmatrix} \begin{bmatrix} x'(t) \\ y'(t) \end{bmatrix}$$

What is the effect of multiplying by the matrix?

- A. The x', y' solution is reflected about a timedependent axis.
- B. The x', y' solution is reflected about a fixed axis.
- C. The x', y' solutions is rotated through a fixed angle.
- D. The x', y' solution is rotated through a timedependent angle.



Consider a Foucault pendulum in the northern hemisphere. We derived the motion of the pendulum in the absence of rotation as x'(t), y'(t). When rotation of the earth is included, we find

$$\begin{bmatrix} \mathbf{x}(t) \\ \mathbf{y}(t) \end{bmatrix} = \begin{bmatrix} \cos\Omega_z t & \sin\Omega_z t \\ -\sin\Omega_z t & \cos\Omega_z t \end{bmatrix} \begin{bmatrix} \mathbf{x}'(t) \\ \mathbf{y}'(t) \end{bmatrix}$$

What is precession frequency of the pendulum?

Α. Ω

B. $\Omega sin\lambda$

- C. $\Omega \cos \lambda$
- D. None of the above.



Consider a Foucault pendulum in the northern hemisphere. Where does the pendulum precess most rapidly?

A. At the equator.B. At 30 degrees N latitude.C. At 45 degrees N latitude.D. At 60 degrees N latitude.E. At the north pole.

