

Faraday's Law

Have said before that ...

\vec{E} fields are created by charges.

\vec{B} fields are created by currents.

~ true, but not the whole truth.

\vec{E} fields can also be created by a changing \vec{B} field

\vec{B} fields can also be created by a changing \vec{E} field.

Faraday's Law relates changing \vec{B} field to \vec{E} field

New terms:

emf (ϵ) = (roughly speaking) a voltage difference capable of generating power. Batteries have an ϵ . Resistors do not, even though $\Delta V = IR$ is a voltage difference.

Technically, E around a loop L is defined as

$$\epsilon = \oint_L \vec{E} \cdot d\vec{l} \quad (\text{Recall } \Delta V = - \oint \vec{E} \cdot d\vec{l})$$

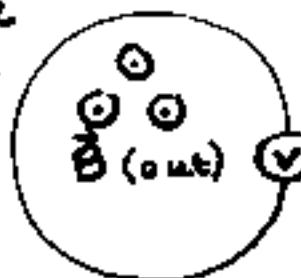
magnetic flux Φ_m over some area is

$$\Phi_m = \int \vec{B} \cdot d\vec{A} = \vec{B} \cdot \vec{A} \quad (\text{if } B \text{ const, A flat})$$

(Like electric flux $\Phi_E = \int \vec{E} \cdot d\vec{A}$)

Faraday's Law:

$$\mathcal{E} = - \frac{d\Phi_B}{dt}$$

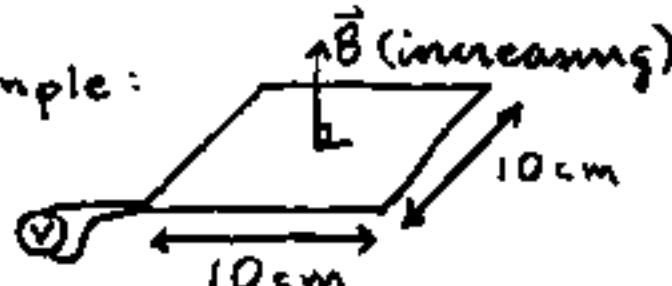
wire
loopvoltmeter
measures \mathcal{E}
around loopif $\vec{B} = \text{const}$
 $\Rightarrow \Phi = \text{const}$
 $\Rightarrow \mathcal{E} = 0$ if \vec{B} changing $\Rightarrow \Phi$ thru loop changing \Rightarrow

$$|\mathcal{E}| = |\frac{d\Phi}{dt}| \neq 0$$

$$\mathcal{E}_{N \text{ loops}} = - N \frac{d\Phi_{(1 \text{ loop})}}{dt}$$

Can change $\Phi = \int \vec{B} \cdot d\vec{A} = \vec{B} \cdot \vec{A}$ thru loop
in several ways:1) change B 2) change area A (by altering area of loop)3) change $\theta = \vec{B} \cdot \vec{A}$ (by turning loop)

Example:



$$A = (0.1m)^2 = 0.01m^2$$

$$\frac{dB}{dt} = +0.1 T/s$$

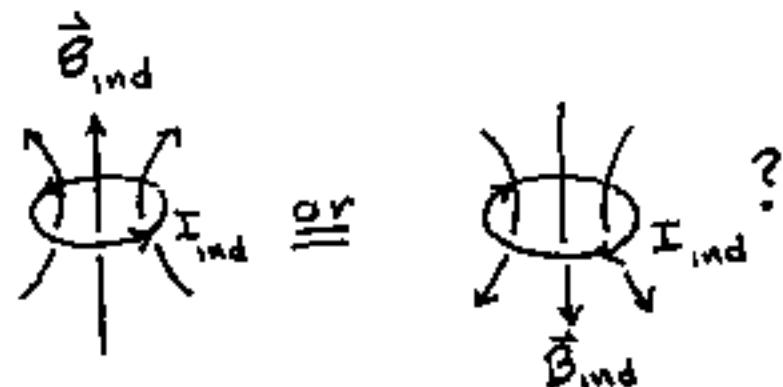
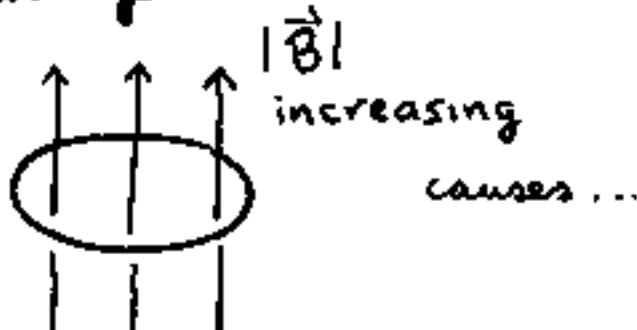
$$|\mathcal{E}| = \frac{d\Phi}{dt} = \frac{d}{dt}(BA) = A \frac{d\theta}{dt} = (0.01)(0.1) = 10^{-3} V$$

If $N = 1000$ turns of coil of wire $\Rightarrow |\mathcal{E}| = 1 V$

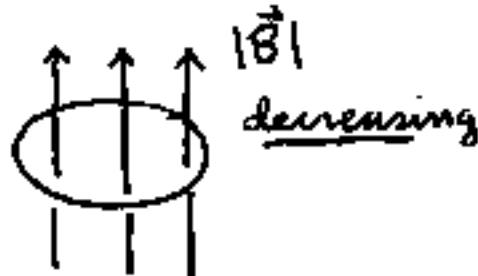
The (-) sign in Faraday's Law is a reminder of ...

Lenz's Law: the induced emf tends to induce a current in the direction which opposes the change in flux.

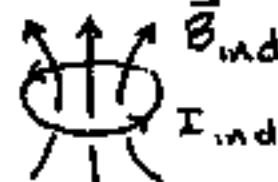
Example:



Answer: \vec{B}_{ind} down fights the change in flux

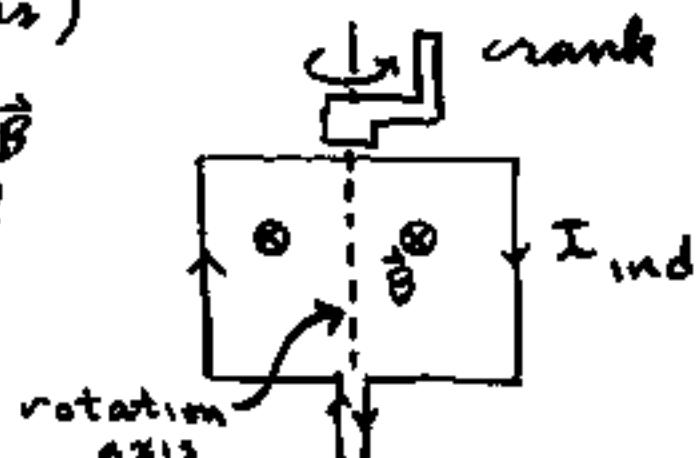


Now, must have \vec{B}_{ind} up to oppose the decrease

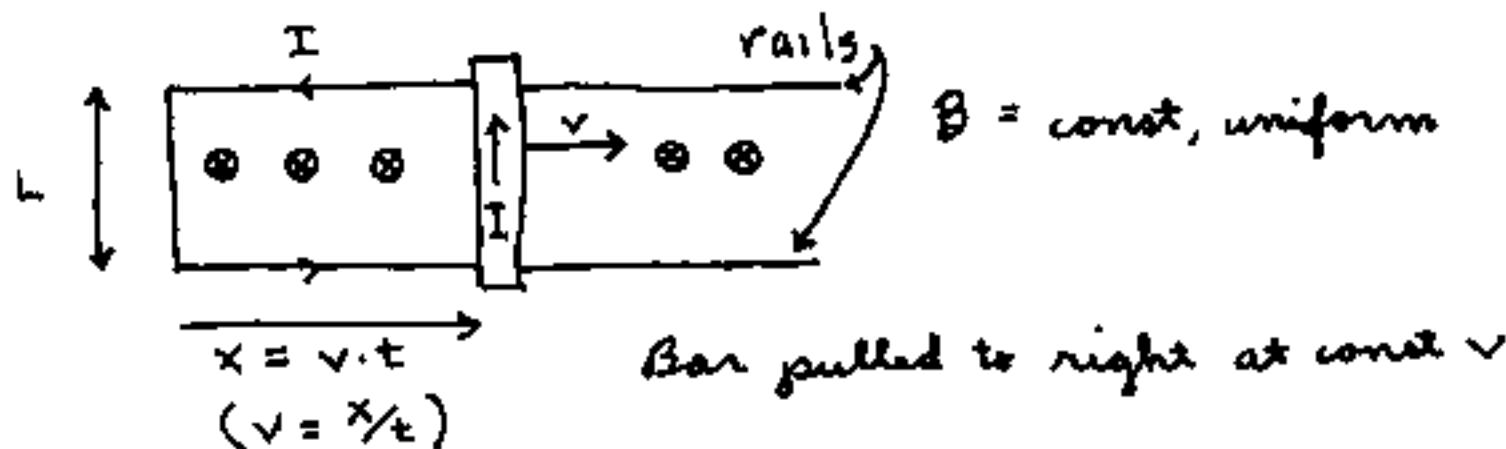


Generators use Faraday's Law to convert mechanical energy into electrical energy (opposite of motors)

wire loop in const \vec{B} field (from external magnet) turned w/ hand crank



Sliding metal bar on metal rails:



Bar + rails form wire loop of area $A = L \cdot x = L v t$

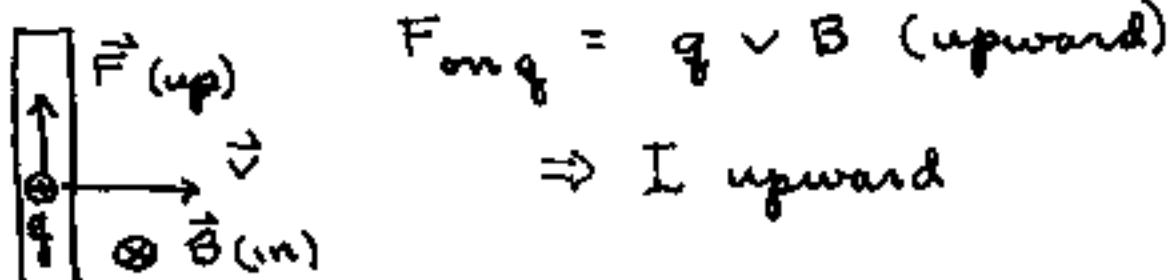
$\Phi = B \cdot A$ increasing $\Rightarrow \mathcal{E} \Rightarrow$ current I induced (ccw)

$$|\mathcal{E}| = \frac{d\Phi}{dt} = \frac{d}{dt}(BA) = \frac{d}{dt}(BLvt) = BLv$$

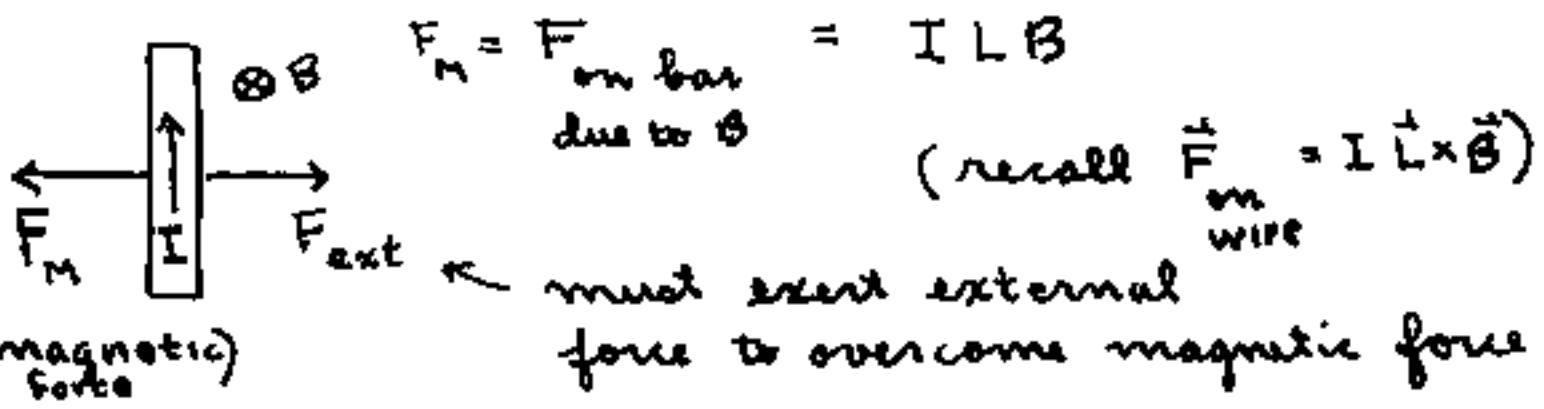
~ example of "motional emf" (motion of bar causes emf)

There is another way to see why I is induced in bar in upward direction:

Charges in bar are moving w/ bar thru \vec{B}



Current I in bar \Rightarrow magnetic force on bar



To maintain const v , must have $F_{\text{ext}} = F_M$

Power delivered by F_{ext} must equal electrical power dissipated in wire

$$P_{\text{ext}} = \frac{dW}{dt} = \frac{d}{dt}(F_{\text{ext}} \cdot x) = F_{\text{ext}} \cdot v$$

$$P_{\text{electrical}} = \epsilon \cdot I \quad (\text{Recall } P = I \cdot V)$$

$$F_{\text{ext}} \cdot v \stackrel{?}{=} \epsilon I \Rightarrow F_M \cdot v = \epsilon \cdot I$$

$$\Rightarrow I L B \cdot v = B L v \cdot I \quad \checkmark \quad (\text{it checks!})$$

Current I in bar is example of Eddy Current

If metal object and source of \vec{B} -field are in relative motion so that there is changing \vec{B} thru some loop within metal, then

Faraday $\Rightarrow \epsilon \Rightarrow I$ (eddy current)

If metal moving, then direction of I always such as to cause force ($F_{\text{wire}} = I \vec{L} \times \vec{B}$) which opposes motion, slows metal.

If eddy current force aided motion, instead of slowing motion, then would get runaway motion
 \Rightarrow free energy \Rightarrow impossible!

In case where loop is stationary and B is changing, then there is no ~~$F_n = q \vec{v} \times \vec{B}$~~ $\vec{F}_n = q \vec{v} \times \vec{B}$

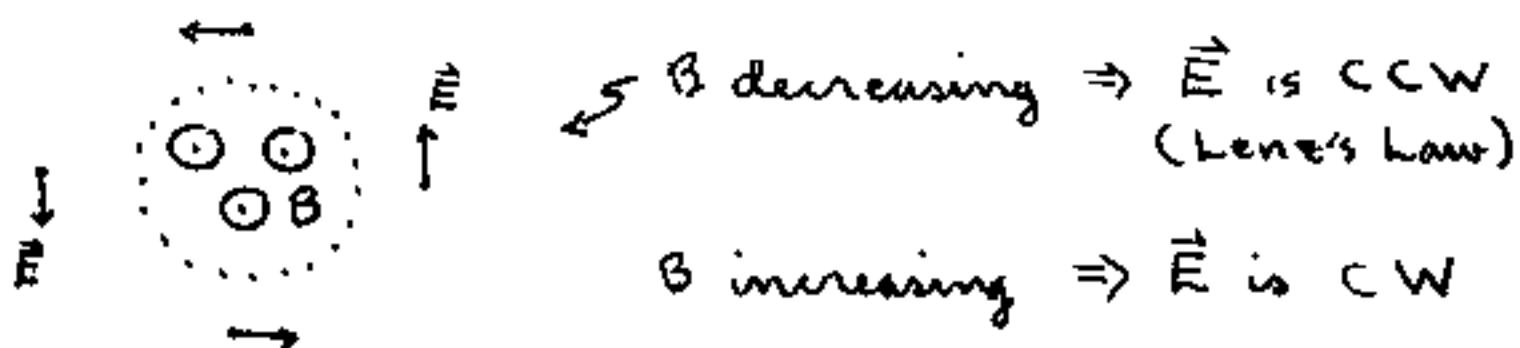
magnetic force on charges in wire, and the only way to explain induced current in wire is to admit creation of \vec{E} -field.

emf E around a (stationary) closed loop is defined as $E = \oint_L \vec{E} \cdot d\vec{l}$.

Faraday's Law $E = - \frac{d\Phi}{dt}$ can be written as

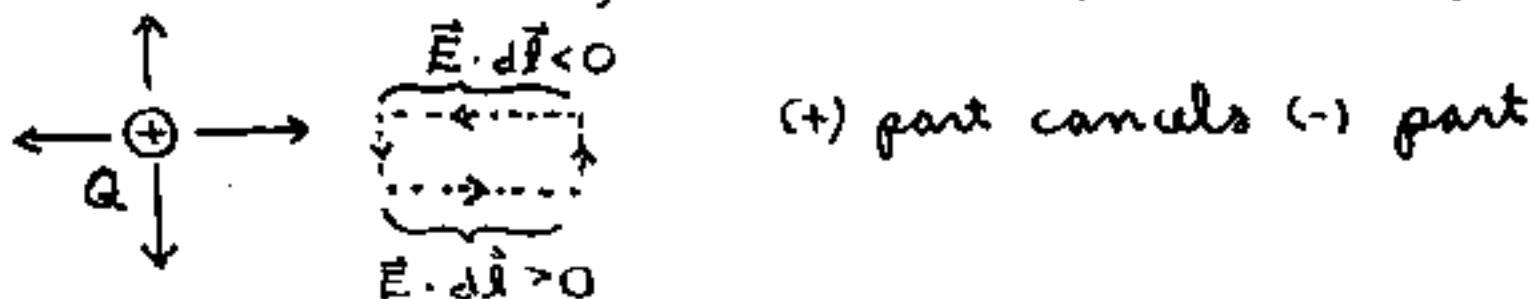
$$\oint_L \vec{E} \cdot d\vec{l} = - \frac{d}{dt} \left(\iint_A \vec{B} \cdot d\vec{A} \right) \quad \begin{array}{l} \text{or loop } L \\ \text{encloses} \\ \text{area } A \end{array}$$

\Rightarrow a changing \vec{B} -field creates an \vec{E} -field



The (non-Coulomb) \vec{E} -field created by $\frac{d\vec{B}}{dt}$ has different properties from Coulomb \vec{E} -field created by charges:

The electrostatic (Coulomb) \vec{E} created by charges always has $\oint \vec{E} \cdot d\vec{l} = 0$ for any loop



If stationary charges only, no currents, no \mathbf{B}

$$\Rightarrow \text{no } \mathbf{E} \Rightarrow \frac{d\Phi}{dt} = 0 \Rightarrow \mathcal{E} = \oint \vec{E} \cdot d\vec{l} = 0$$

Inductors (inductor = coil of wire)

Important fact: magnetic flux Φ_M ($= \vec{B} \cdot \vec{A}$) is proportional to current I making the Φ_M .

All our formulas for \vec{B} show $B \propto I$:

Biot Savart:

$$d\vec{B} = \frac{\mu_0 I}{4\pi} \frac{d\vec{l} \times \hat{r}}{r^2},$$

Ampere:

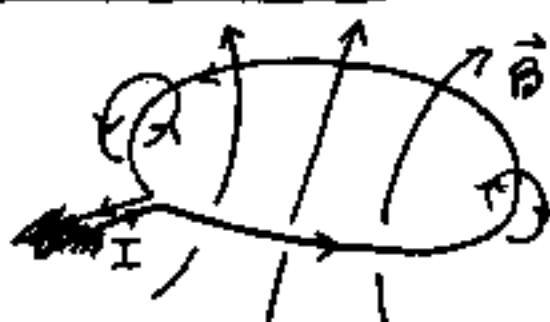
$$\oint \vec{B} \cdot d\vec{l} = \mu_0 I_{\text{thru}}$$

$$\Rightarrow \text{flux } \Phi \propto B \propto I \Rightarrow \Phi \propto I$$

Definition: Self-inductance L of coil of wire

$$\boxed{\Phi_M = L I}$$

($L = \Phi/I = \text{const independent of } I$)



current $I \Rightarrow B \Rightarrow \Phi_M$

$$\begin{aligned} \text{units of inductance } [L] &= \frac{[\Phi]}{[I]} = \frac{T \cdot m^2}{A} = \frac{V \cdot s}{A} \\ &= 1 \text{ henry (H)} \end{aligned}$$

An inductor is a coil of wire. One or a few loops of wire has $L \approx 1 \mu H$ (usually insignificant); a coil w/ thousands of turns has $L \approx 1 H$ (big!).

$$\Phi = L \cdot I \Rightarrow \frac{d\Phi}{dt} = L \frac{dI}{dt} = -\epsilon$$

$$\boxed{\epsilon = -L \frac{dI}{dt}}$$

Changing the current in an inductor creates an emf which opposes the change in I .

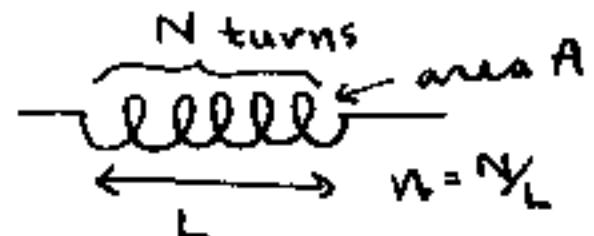
Induced emf often called "back emf"

\Rightarrow it is difficult (requires big external voltage) to change quickly the current in an inductor.

\Rightarrow The current in an inductor cannot change instantly. (If it did (or tried to) would have infinite ϵ , infinite E to fight change.)

Self-inductance of solenoid:

$$\text{If coil long, } B = \mu_0 n I$$



$$\Phi = N B A = N \mu_0 n I A$$

$$\frac{\Phi}{I} = \frac{N \mu_0 n A}{L}$$

↑ ↑
inductance (don't confuse the L's) length

Computing the inductance of a single turn coil (or a few turn coil) is quite messy because the B -field in a loop of wire is non-uniform. So computing the magnetic flux $\Phi_n = \int \vec{B} \cdot d\vec{A}$ is difficult (messy).

Magnetic Energy Density

Recall that for capacitor C , stored energy $U = \frac{1}{2} C V^2$
 energy is stored in E-field, energy density =

$$u_E = \frac{U}{\text{vol.}} = \frac{1}{2} \epsilon_0 E^2$$

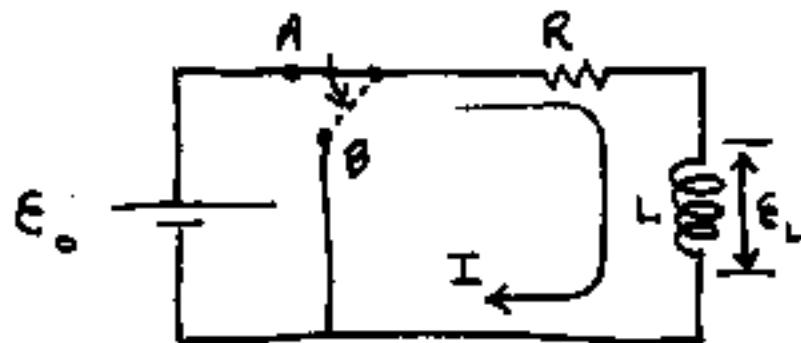
For an inductor L , with current I , stored energy is
 $U = \frac{1}{2} L I^2$. The energy is stored in the B-field.
 energy density is $u_B = \frac{U}{\text{vol.}} = \frac{1}{2} \frac{B^2}{\mu_0}$

It takes work to get current flowing in an inductor
 (must work against the back emf which opposes any
 change in current). That work = $U = \frac{1}{2} L I^2$ is
 stored in the inductor's magnetic field.

LR circuits (Circuits w/ L's & R's)

3 things to remember:

- $|E_L| = L \left| \frac{dI}{dt} \right|$ ~the inductor acts like a battery if its current is changing
- I thru L cannot change instantly.
 (because that would cause infinite E)
- In steady state (after long time) $I = \text{const} \Leftrightarrow E_L = 0$
 $E_L = 0 \Rightarrow$ inductor acts like short (zero-R wire)



Switch at A for long time:

$$I = \text{const}, E_L = 0$$

$$I = \frac{E_0}{R}$$

At $t=0$, switch \rightarrow B:



$$\text{At } t=0+, I = I_0 = \frac{E_0}{R}$$

E_L keeps current going!

$$\text{Loop Law: } IR + |E_L| = -L \frac{dI}{dt}$$

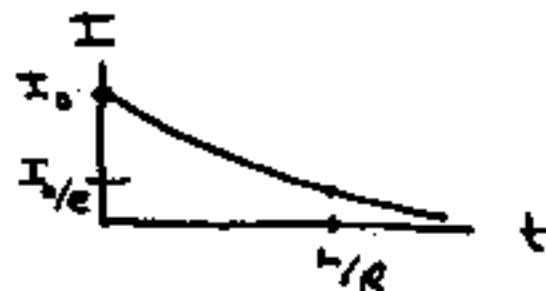
$$\left[\frac{dI}{dt} < 0 \Rightarrow -L \frac{dI}{dt} > 0 \right]$$

$$\frac{dI}{dt} = -\left(\frac{R}{L}\right) I \quad \sim \text{a differential eqn w/ exponential sol'n}$$

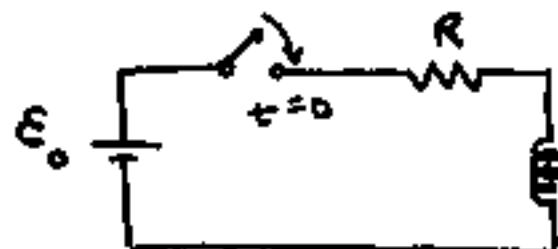
$$\Rightarrow I = I_0 e^{-\left(\frac{R}{L}\right) \cdot t} = I_0 e^{-t/(L/R)}$$

$\frac{L}{R}$ = time constant of LR circuit

= time for anything to change by factor of e



Another LR circuit:



$$t = 0+$$

$$I = 0, \quad |E_L| = \left| L \frac{dI}{dt} \right| = E_0$$

$$\text{Since } E_0 = IR + L \frac{dI}{dt} \quad (\text{by Loop Law})$$

$$\text{and } I = 0 \quad (\text{at } t = 0+)$$

$$\text{As } t \uparrow, \quad I \uparrow, \quad V_R = IR \uparrow, \quad |E_L| = \left| L \frac{dI}{dt} \right| \downarrow$$

$$\text{As } t \rightarrow \infty, \quad |E_L| \rightarrow 0, \quad E_0 = IR$$

