

Poisson's equation tells us that  $\nabla^2 V = -\frac{\rho}{\varepsilon_0}$ If the charge density throughout some volume is zero, what else *must* be true throughout that volume: A) V=0 B) E=0

C) Both V and E must be zero

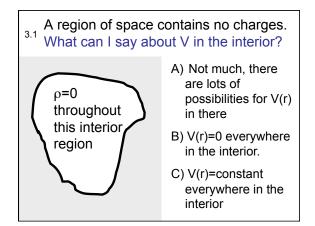
D) None of the above is

necessarily true

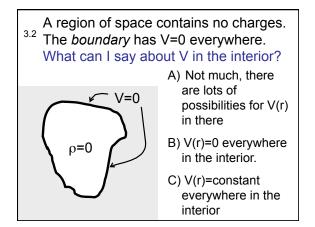
Why is 
$$\oint \vec{\mathbf{E}} \cdot d\vec{\mathbf{L}}$$
 =0 in electrostatics?

a) Because  $\nabla X \vec{E} = 0$ 

- b) Because E is a conservative field
- c) Because the potential between two points is independent of the path
- d) All of the above
- e) NONE of the above it's not true!







<sup>3.3</sup> Two very strong (big C) ideal capacitors are well separated. If they are connected by 2 thin conducting wires, as shown, is this electrostatic			
situatio 	n physically stable? A)Yes B)No <u>C)???</u>		



<sup>3.4</sup> Two very strong (big C) ideal capacitors are well separated. What if they are connected by one thin conducting wire, is this electrostatic		
situation physically stable? A)Yes B)No C)???	-Q -Q +++++++++++++++++++++++++++++++++	



### General properties of solutions of $\nabla^2$ V=0

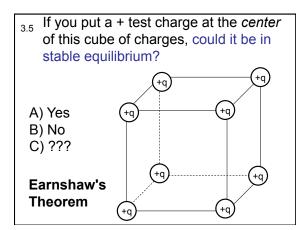
(1)V has no local maxima or minima inside. Maxima and minima are located on surrounding boundary.

(2)V is boring. (I mean "smooth & continuous" everywhere).

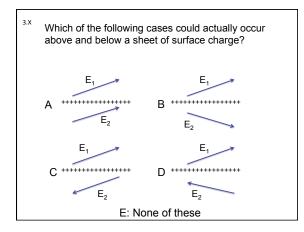
 $(3)V(\mathbf{r})$  = average of V over any surrounding sphere:

$$V(\vec{r}) = \frac{1}{4\pi R^2} \cdot \oint_{\substack{Sphere \text{ with}\\radius R\\around \bar{r}}} V da$$

(4) V is unique: The solution of to the Laplace eq. is uniquely determined if V is specified on the boundary surface around the volume.







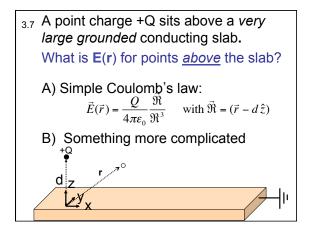


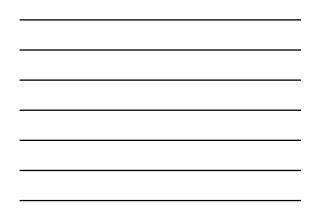
METHOD OF IMAGES

# Class Activities: Method of Images

# Whiteboards Method of Images I set up the "method of images" problem (with +O above, and -Q below), and had I THEM, in pair, while the formula for V(x, y2), (They straggled surprisingly with this!) I then had them evaluate V(x, y0) and V(anything >> infinity). Lastly, I had the faster groups work out Ex, Ey, and/or Ez, and evaluate it on the plane.

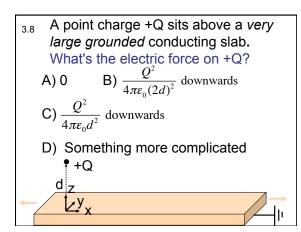
od of Images? On paper (don't forget your name!) in your own words (by it is the idea behind the method of images? What does it What is its relation to the uniqueness theorem?<sup>4</sup> and collect

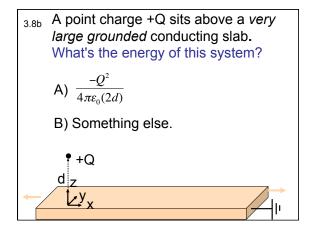




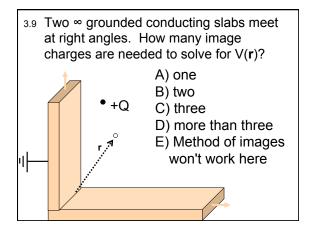
Whiteboard:

Calculate voltage for 2 point charges a distance "d" above and below the origin. Where is V(r)=0?

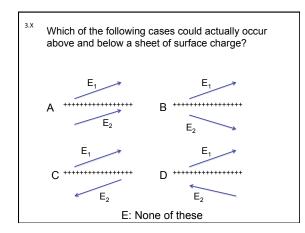




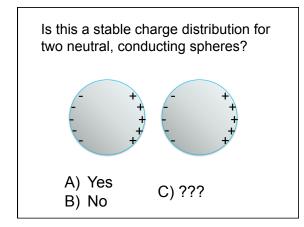




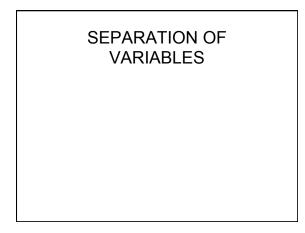












Class Activities: Sep of Var (1)

Discussion Questions for Lecture (from UIUC) 1.) What are the physical reasons/motivation for wanting to solve the Laplace equation or the Poisson equation? 2.) What is the general form of the 1-D solution to Laplaces equation? 3.) The nature of Laplace's equation is such that it tolerates/allows NO local maxima or minima for V(f); all extrema of V(f) must occur at endpoints/boundaries. Why?

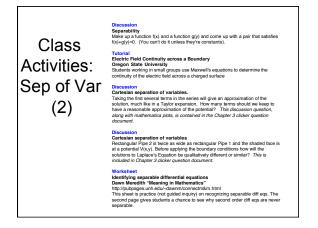
Whiteboards Shih and Cosh Draw sinh and cosh, is it even/odd, what's the curvature, behaviour as x=0, infinity, what's cosh(p), etc... Show my mathematica solution in powerpoint (i did "not" show the 20 "0-V0-0 V0" boundary value profelmer, caller aftemative, separation, variables.ht")

### oards

Whiteboards Boundary conditions on E One persistent difficulty that students have is an inability to recreate the mathematical targets obtermine the boundary conditions on the parallel and perpendicular components of E. After watching 3 continuous semesters of this course, I strongly recommend having a whiteboard or worksheat activity where students are asked to derive those boundary conditions given a surface charge

### Simulation

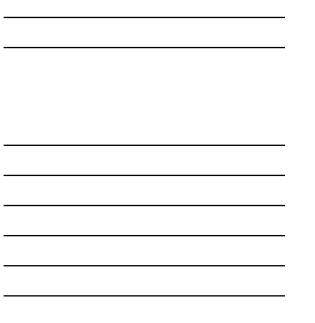
Simulation Fourier Show the PhET Fourier sim. Also show the mathematic notebook I made where we can 'look' at the Legendre Polynomials. See http://phet.colorado.edu/index.php



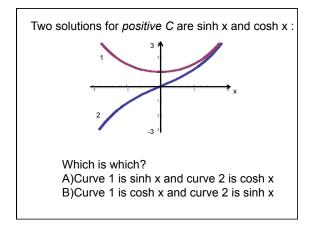
Class Activities: Sep of Var (3)

er ce<sup>2</sup>s Equation ce<sup>3</sup>s Equation Dublin University (Tutorials 9-16, page 10) al on Laplace's equation. Conducting oylinder in Elield. First describe appens to the oylinder when placed in the Elield. Do separation of <sup>to a</sup> in rolindrical coordinates.

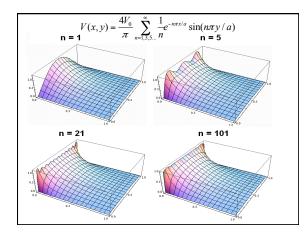
Griffithe by Inquiry (Lab 2): Laplace's Equation and Boundary Value problems Griffithe by Inquiry (Lab 3): 2D Boundary Value problems in Cartesian coordinates Griffithe by Inquiry (Lab 4): 2D Boundary Value problems in Cylindrical coordinates



# CARTESIAN COORDINATES









Second uniqueness Theorem: In a volume surrounded by conductors and containing a specified charge density  $\rho(r)$ , the electric field is uniquely determined if the total charge on each conductor is given. (The region as a whole can be bounded by another conductor, or else unbounded.)

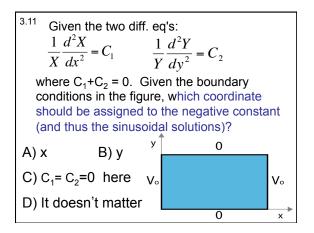
Griffiths, 3.1.6

Say you have three functions f(x), g(y) and h(z). f(x) only depends on 'x' but not on 'y' and 'z'. g(y) only depends on 'y' but not on 'x' and 'z'. h(z) only depends on 'z' but not on 'z' and 'y'. If f(x) + g(y) + h(z) = 0 for all x, y, z, then: A)All three functions are constants (i.e. they do not depend on x, y, z at all.) B)At least one of these functions has to be zero everywhere. C)All of these functions have to be zero

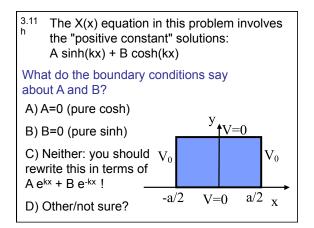
evervwhere



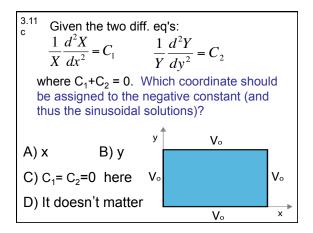
- 3.10 Suppose V₁(r) and V₂(r) are linearly independent functions which *both* solve Laplace's equation, ∇²V = 0 Does aV₁(r)+bV₂(r) also solve it (with a and b constants)?
  A) Yes. The Laplacian is a linear operator
  B) No. The uniqueness theorem says this
- B) No. The *uniqueness theorem* says this scenario is impossible, there are never two independent solutions!
- C) It is a definite yes or no, but the *reasons* given above just aren't right!D) It depends...



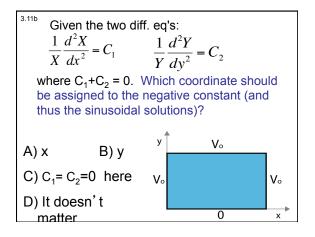




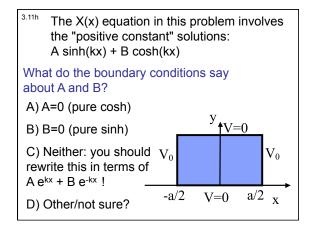




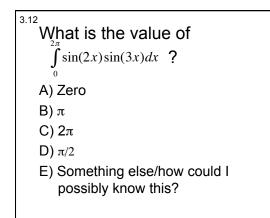








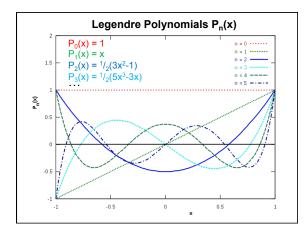




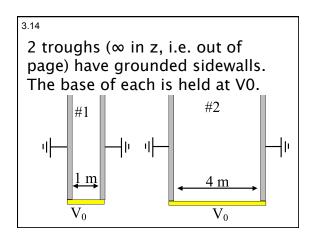
## 'Separation of Variables' is:

A) ... easy - piece of cake!

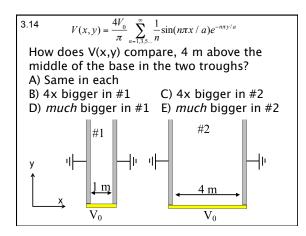
- B) ... I'm getting the hang of it. More examples please (maybe in spherical coordinates?).
- C) ... somewhat confusing.
- D) ... really hard! What's going on?
- E) Fourier's trick just doesn't make any sense (or other things, such as: 'Why did we write V(x,y,z) = X(x)\*Y(y)\*Z(z) ?')



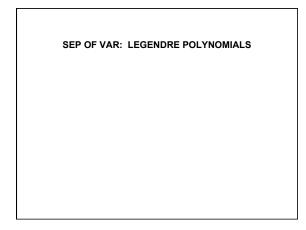












**Orthogonality**  

$$\int_{-1}^{1} P_{l}(x)P_{m}(x)dx = \begin{cases} \frac{2}{2l+1} & \text{if } l = m\\ 0 & \text{if } l \neq m \end{cases}$$
With:  $x = \cos\theta$  and:  $dx = -\sin\theta d\theta$ , we get:  

$$\int_{0}^{\pi} P_{l}(\cos\theta)P_{m}(\cos\theta)\sin\theta d\theta = \begin{cases} \frac{2}{2l+1} & \text{if } l = m\\ 0 & \text{if } l \neq m \end{cases}$$

<sup>3.10</sup> Suppose V<sub>1</sub>(**r**) and V<sub>2</sub>(**r**) are linearly independent functions which *both* solve Laplace's equation,  $\nabla^2 V = 0$ 

Does  $aV_1(\mathbf{r})+bV_2(\mathbf{r})$  also solve it (with 'a' and 'b' constants)?

- A) Yes. The Laplacean is a linear operator
- B) No. The *uniqueness theorem* says this scenario is impossible, there are never two independent solutions!
- C) It is a definite yes or no, but the *reasons* given above just aren't right!D) It depends...

<sup>3.15</sup> Given  $\nabla^2 V = 0$  in Cartesian coords, we separated V(x,y,z) = X(x)Y(y)Z(z). Will this approach work in spherical coordinates, i.e. can we separate V(r, $\theta, \phi$ ) = R(r)P( $\theta$ )F( $\phi$ )?

A) Sure.

- B) Not quite the angular components cannot be isolated, e.g.  $f(r,\theta,\phi) = R(r)Y(\theta,\phi)$
- C) It won't work at all because the spherical form of Laplace's Equation has cross terms in it (see the front cover of Griffiths)

3.16 The Rodrigues formula for generating the Legendre Polynomials is  $P_{l}(x) = \frac{1}{2^{l} l!} \left(\frac{dy}{dx}\right)^{l} (x^{2} - 1)^{l}$ 

If the Legendre polynomials are orthogonal, are the leading coefficients  $\frac{1}{2^{l}l!}$  necessary to maintain orthogonality?

- A) Yes,  $f_m(x)$  must be properly scaled for it to be orthogonal to  $f_n(x)$ .
- B) No, the constants will only rescale the integral

<sup>3.17</sup> Given 
$$V(\theta) = \sum_{l=0}^{\infty} C_l P_l(\cos \theta)$$
  
(The P<sub>1</sub>'s are Legendre polynomials.)  
If we want to isolate/determine the coefficients  
 $C_1$  in that series, multiply both sides by:  
A) P<sub>m</sub>( $\theta$ )  
B) P<sub>m</sub>(cos $\theta$ )  
C) P<sub>m</sub>( $\theta$ ) sin $\theta$   
D) P<sub>m</sub>(cos $\theta$ ) sin $\theta$   
E) something entirely different

$$\int_{0}^{\pi} P_{l}(\cos\theta) P_{m}(\cos\theta) \sin\theta d\theta = \begin{cases} \frac{2}{2l+1} & \text{if } l = m \\ 0 & \text{if } l \neq m \end{cases}$$
$$\int_{-1}^{1} P_{l}(x) P_{m}(x) dx = \begin{cases} \frac{2}{2l+1} & \text{if } l = m \\ 0 & \text{if } l \neq m \end{cases}$$

3.18  

$$V(r,\theta) = \sum_{l=0}^{\infty} \left( A_l r^l + \frac{B_l}{r^{l+1}} \right) P_l(\cos\theta)$$
Suppose V on a spherical shell is constant, i.e. V(R,  $\theta$ ) = V<sub>0</sub>.  
Which terms do you expect to appear when finding V(outside) ?  
A) Many A<sub>l</sub> terms (but no B<sub>l</sub>'s)  
B) Many B<sub>l</sub> terms (but no A<sub>l</sub>'s)  
C) Just A<sub>0</sub>  
D) Just B<sub>0</sub>  
E) Something else!!

<sup>3.18</sup>  
b
$$V(r,\theta) = \sum_{l=0}^{\infty} \left( A_l r^l + \frac{B_l}{r^{l+1}} \right) P_l(\cos\theta)$$
Suppose V on a spherical shell is constant, i.e. V(R,  $\theta$ ) = V<sub>0</sub>.  
Which terms do you expect to appear when finding V(inside) ?  
A) Many A<sub>l</sub> terms (but no B<sub>l</sub>'s)  
B) Many B<sub>l</sub> terms (but no A<sub>l</sub>'s)  
C) Just A<sub>0</sub>  
D) Just B<sub>0</sub>  
E) Something else!

3.19a  $P_{0}(\cos\theta) = 1, \qquad P_{1}(\cos\theta) = \cos\theta$   $P_{2}(\cos\theta) = \frac{3}{2}\cos^{2}\theta - \frac{1}{2}, \qquad P_{3}(\cos\theta) = \frac{5}{2}\cos^{3}\theta - \frac{3}{2}\cos\theta$ Can you write the function  $V_{0}(1 + \cos^{2}\theta)$ as a sum of Legendre Polynomials?  $V_{0}(1 + \cos^{2}\theta) \stackrel{???}{=} \sum_{l=0}^{\infty} C_{l}P_{l}(\cos\theta)$ A)No, it cannot be done B) It would require an infinite sum of terms C) It would only involve P<sub>2</sub> D) It would involve all three of P<sub>0</sub>, P<sub>1</sub> AND P<sub>2</sub> E) Something else/none of the above

3.19  $V(r,\theta) = \sum_{l=0}^{\infty} \left( A_l r^l + \frac{B_l}{r^{l+1}} \right) P_l(\cos\theta)$ Suppose V on a spherical shell is  $V(R,\theta) = V_0(1 + \cos^2\theta)$ Which terms do you expect to appear when finding V(inside) ? A) Many A\_l terms (but no B\_l's) B) Many B\_l terms (but no A\_l's) C) Just A\_0 and A\_2 D) Just B\_0 and B\_2

E) Something else!

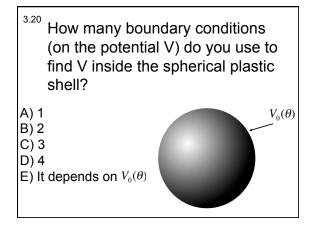
<sup>3.19</sup>  

$$V(r,\theta) = \sum_{l=0}^{\infty} \left( A_l r^l + \frac{B_l}{r^{l+1}} \right) P_l(\cos\theta)$$
Suppose V on a spherical shell is  

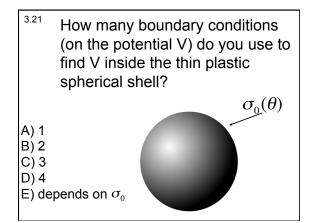
$$V(R,\theta) = V_0(1 + \cos^2\theta)$$
Which terms do you expect to appear  
when finding V(outside) ?  
A) Many A<sub>l</sub> terms (but no B<sub>l</sub>'s)  
B) Many B<sub>l</sub> terms (but no A<sub>l</sub>'s)  
C) Just A<sub>0</sub> and A<sub>2</sub>  
D) Just B<sub>0</sub> and B<sub>2</sub>  
E) Something else!

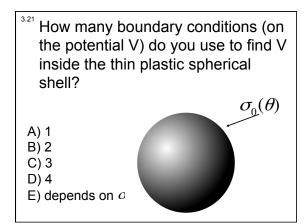
$$\begin{split} & \text{MD11-2} \\ & \text{Suppose that applying boundary} \\ & \text{conditions to Laplace's equation} \\ & \text{leads to an equation of the form:} \\ & \\ & \sum_{I=0}^{\infty} C_{II} P\left(\cos\theta\right) = 4 + 3\cos\theta \\ & P_0(x) = 1 \\ & P_1(x) = x \\ & P_2(x) = (3x^2 - 1)/2 \\ & \text{Can you solve for the coefficients, the } C_1 \text{'s ?} \\ & \text{A)No, you need at least one more equation to solve for any the } \\ & \text{C's.} \\ & \text{B) Yes, you have enough info to solve for all of the C's } \\ & \text{C)Partially. Can solve for C}_0 \text{ and } C_1, \text{ but cannot solve for the other C's.} \\ & \text{D)Partially. Can solve for C}_0, \text{ but cannot solve for the other C's.} \end{split}$$







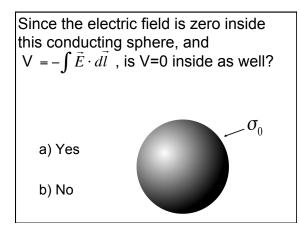


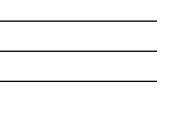


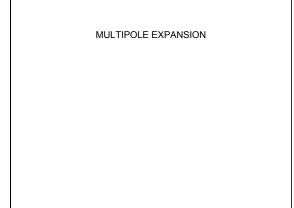


<sup>3.21</sup>
Does the previous answer change at all if you're asked for V *outside* the sphere?
a) yes

b) No



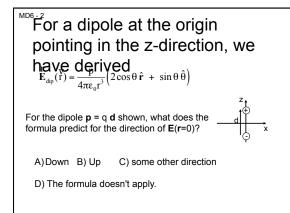




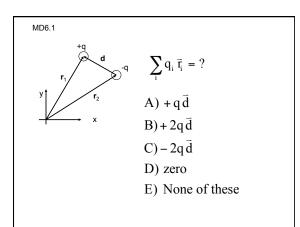
Class Activities: Multipole

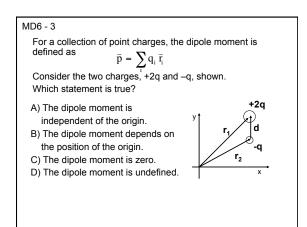
Tutorial Multipole expansion: "Discrete" activity Oregon State University Students work in small groups to create power series expansions for the electrostatic potential due to two electric charges separated by a distance D. Griffiths by Inquiry (Lab 6): Multipole expansions

Discussion Questions for lecture (from UIUC): 1) Mmy should we care about approximate solutions for the scalar potential V(r) ardor E(r)? 2) What are electric multipole moments of an electric charge distribution? 3) When is it appropriate to use such approximate solutions for the scalar potential V(r) and or E(r)?



<sup>MD6-2</sup> At the end of last class we derived the potential for a dipole at the origin pointing in the z-direction. Using  $\mathbf{E} = -\nabla V$  we can find the E-field in spherical coordinates:  $\mathbf{E}_{dip}(\mathbf{r}) = \frac{\mathbf{p}}{4\pi\epsilon_0 \mathbf{r}^3} (2\cos\theta \,\hat{\mathbf{r}} + \sin\theta \,\hat{\theta})$ For the dipole  $\mathbf{p} = \mathbf{q} \, \mathbf{d}$  shown, what does the formula predict for the direction of  $\mathbf{E}(\mathbf{r}=0)$ ? A)Down B) Up C) some other direction D) The formula doesn't apply.

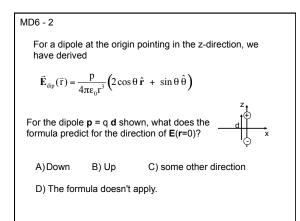




3.22a A small dipole (dipole moment p=qd) points in the z direction. We have derived $V(\bar{r}) \approx \frac{1}{4\pi\varepsilon_0} \frac{qdz}{r_r}$		
Which of the following is correct (and "coordinate free")?		
A) $V(\bar{r}) = \frac{1}{4\pi\varepsilon_0} \frac{\bar{p}\cdot\hat{r}}{r^2}$ B) $V(\bar{r}) = \frac{1}{4\pi\varepsilon_0} \frac{\bar{p}\cdot\hat{r}}{r^3}$		
C) $V(\vec{r}) = \frac{1}{4\pi\varepsilon_0} \frac{\vec{p} \cdot \vec{r}}{r}$ D) $V(\vec{r}) = \frac{1}{4\pi\varepsilon_0} \frac{\vec{p} \times \hat{r}}{r}$		
E) None of these		



<sup>3.22</sup> b An ideal dipole (tiny dipole moment p=qd) points in the z direction. We have derived  $\vec{E}(\vec{r}) = \frac{p}{4\pi\epsilon_0 r} (2\cos\theta \hat{r} + \sin\theta \vec{\theta})$ Sketch this E field... (What would change if the dipole separation d was *not* so tiny?)



3.22 c

You have a physical dipole, +q and -q a finite distance d apart.

When can you use the expression:

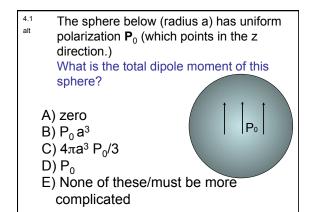
$$V(\vec{r}) = \frac{1}{4\pi\varepsilon_0} \frac{p \cdot r}{r^2}$$

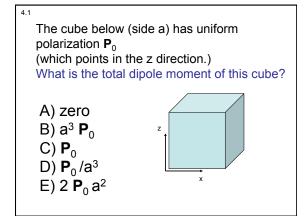
A) This is an exact expression everywhere.

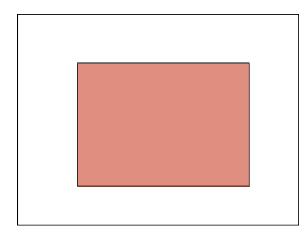
B) It's valid for large r

C) It's valid for small r

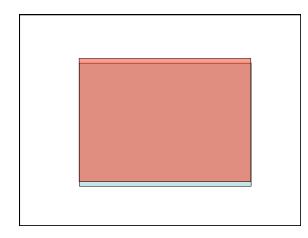
D)?

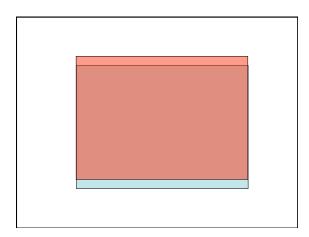






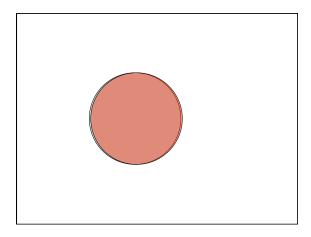




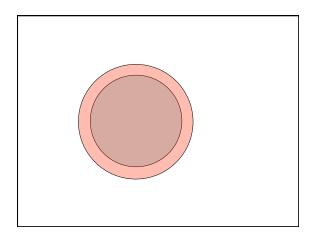












### 3.22 d

You have a physical dipole, +q and -q, a finite distance d apart. When can you use the expression

$$V(r) = \frac{1}{4\pi\varepsilon_0} \sum \frac{q_i}{\Re}$$

A) This is an exact expression everywhere.

- B) It's valid for large r
- C) It's valid for small r

D)?

3.23

Griffiths argues that the force *on* a dipole in an E field is:  $\vec{F} = (\vec{p} \bullet \vec{\nabla})\vec{E}$ 

If the dipole **p** points in the z direction, what direction is the force?

A) Also in the z directionB) perpendicular to zC) it could point in any direction

3.23

Griffiths argues that the force on a <u>neutral</u> dipole in an external E field is:

$$\vec{\mathbf{F}} = (\vec{\mathbf{p}} \bullet \vec{\nabla}) \vec{\mathbf{E}}_{ext}$$

If the dipole **p** points in the z direction, what direction is the force?

A) Also in the z direction

B) perpendicular to z

C) it could point in any direction

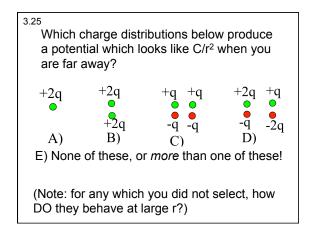
D) the force is zero because the dipole is neutral

3.24

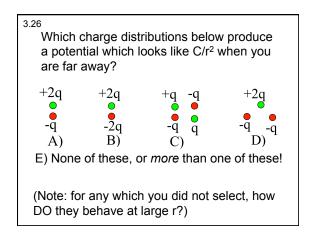
Griffiths argues that the force on a dipole in an E field is:  $\vec{F} = (\vec{p} \cdot \vec{\nabla})\vec{E}$ 

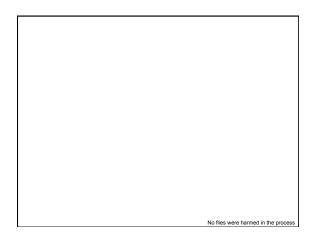
If the dipole  $\mathbf{p}$  points in the z direction, what can you say about  $\mathbf{E}$  if I tell you the force is in the x direction?

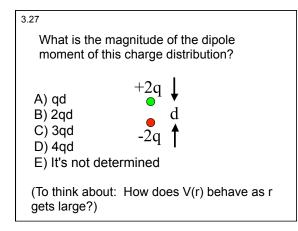
- A) **E** simply points in the x direction
- B) Ez must depend on x
- C) Ez must depend on z
- D) Ex must depend on x
- E) Ex must depend on z



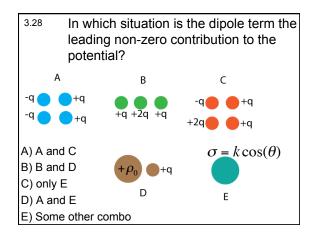




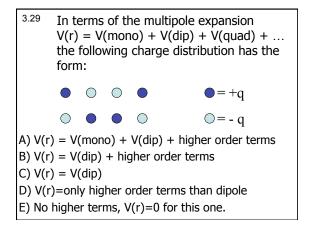




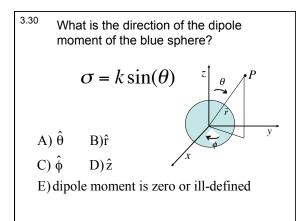














On paper (don't forget your name!) in your own words (by yourself):

What is the idea behind the multipole expansion? What does it accomplish? In what limits/cases is it useful?